1 Introduction:

Typical ASIC design flow requires several general steps that are perhaps best illustrated using a process flow chart:

**Figure 1: Process Flow Chart**

**HDL Design Capture**
- Design Specification
  - Behavioral Description
  - RTL Description
- RTL Functionality Verified?
  - Yes
  - No
- Verification Vectors

**HDL Design Synthesis**
- RTL to Logic
- Logic Optimization
- Logic to Technology
- Timing/Area Optimization
- Constraints
- Scan Path Insertion & Test Vector Generation
- Netlist
  - Logic & Timing Verified?
  - Yes
  - No

**Design Implementation**
- Floor Planning
- Place & Route
- Physical Layout
- Layout
  - Function & Timing Verified?
  - Yes
  - No
- Physical Layout
- Chip Production
This tutorial is meant only to provide the reader with a brief introduction to those portions of the design process that occur in the HDL Design Capture and HDL Design Synthesis phases, and a brief overview of the design automation tools typically used for these portions of the design process. The detailed methodology and strategies required to produce successful designs will be discussed throughout the course lectures.

This tutorial is broken up as follows:

- Section 2 is an overview of the design, synthesis and verification process
- Section 3 is an overview of the tools to be used
- Section 4 discusses pre-synthesis simulation and verification using Verilog. This step is important to ensure that your Verilog input for Synopsys is correct.
- Section 5 discusses logic synthesis using Synopsys. This is the step in which the Verilog code is converted to a gate level design.
- Section 6 discusses post-synthesis simulation and verification using Verilog. This simulation is run to check that the above two steps were correctly conducted.
- Section 7 discusses post-synthesis timing verification using Cadence Pearl. This timing verification is carried out as a check on the timing of the gate level design produced by Synopsys.
- Section 8 discusses how to run these tools using scripts. Most of the discussion in Sections 4-7 are centered on running these tools interactively. Sometimes these tools can take a long time to run and running the tool in batch mode using a script is useful.
- Section 9 summarizes how to run the tools remotely. You can do all of the steps above over a telnet session if you want.
- Section 10 discusses the Veriwell PC Verilog simulator. You can download this simulator and use it instead of Verilog-XL for pre-synthesis simulations.

2  The Design Process:

Referring to the figure on the previous page, the HDL Design Capture phase implements the “top-down” methodology of design. It takes a designer from abstract concept or algorithm down to hardware in manageable and verifiable steps. This involves developing a design specification that will be used to create a high level behavioral abstraction with high-level programming languages such as C/C++. Additionally, this model may also be created using the Verilog hardware description language (HDL). The behavioral model should be simulated in order to verify that the desired functionality is captured completely and correctly. The behavioral abstraction is then used as a reference to create and refine a synthesizable register transfer level (RTL) abstraction that captures the desired functionality required by the design specification.

With Verilog, the difference between a purely “behavioral” and an RTL abstraction may appear subtle at this point, but it is important that you come away from the course with a clear understanding of the distinction between them. Generally, we will represent designs in Verilog at three levels of abstraction:

- The Behavioral Level: a design is implemented in terms of the desired algorithm, much like software programming and without regard for actual hardware. As a result, a Verilog model written at the behavioral level usually can not be synthesized into hardware by the synthesis tools.
• The Register Transfer Level: a design is implicitly modeled in terms of hardware registers and the combinational logic that exists between them to provide the desired data processing. The key feature is that an RTL level description can be translated into hardware by the synthesis tools.
• The Structural Level: a design is realized through explicit instances of logic primitives and the interconnects between them, and is also referred to as a “gate-level” model.

The **HDL Design Capture** phase is completed with “pre-synthesis” simulations to verify that the RTL abstraction fully provides the desired functionality. The functional verification of the design that occurs at this point must be as complete and thorough as possible. This requires that the designer fully understand both the design specification and the RTL implementation. The test vectors employed during simulation should provide the coverage necessary to ensure the design will meet specifications.

The **HDL Design Synthesis** phase involves using a synthesis tool to:

• Translate the abstract RTL design description to register elements and combinational logic,
• Optimize the combinational logic by minimizing, flattening and factoring the resulting boolean equations,
• Translate the optimized logic level description to a gate level description using cells from the specified technology library,
• Optimize the gate level description using cell substitution to meet the specified area and timing constraints, and
• Produce a gate level netlist of the optimized circuit with accurate cell timing information.

**HDL Design Synthesis** finishes with “post-synthesis” simulations to verify that the gate level circuit fully provides the desired functionality **and** meets the appropriate timing requirements.

### 3 Tools:

The specification for the design used in this tutorial is for a 4 bit down-counter with inputs named “in”, “latch” “dec” and “clock,” and an output named “zero.” The design provides the following functionality:
• The internal count value is loaded from “in” on a positive clock edge only when “latch” is high.
• The count value decrements by 1 on a positive clock edge when “dec” is high.
• When the count value is 0, no further decrementing occurs.
• The “zero” flag is active high whenever the count value is 0.

A behavioral model written using Verilog as a high level programming language may look like the following:

```verilog
always@(latch)
begin
  if(latch)
```
\begin{verbatim}
value = in;
else
  while (value > 0)
  begin
    value = value - 1;
    zero = (value == 0);
  end
end
\end{verbatim}

You will find files necessary for this tutorial in the \textit{ece520_info/tutorials/tutor1/bin/} locker. These include an RTL description of a simple down counter written in Verilog (count.v), Verilog test fixtures (testcount.v) for pre-synthesis (testpre.v) and post-synthesis (testpost.v, simpost) functional verification, and a command script (count.dc) to guide the Synopsys synthesis tool’s translation of the RTL description of the counter to a gate-level netlist. You will also find the verilog test fixtures (testmin.v, testmax.v) and the scripts (simmin, simmax) required to run back annotated timing analyses. The directory also contains all the files necessary to run the static timing analysis tool, \textit{Pearl}. These files include the scripts to direct Pearl (count_final.cmd, all.cmd) and the library file (std-cell.tech). Finally there is an example script for running remotely (runmeall).

The tutorial is separated into the following parts:
\begin{itemize}
  \item Section 4 “Pre-Synthesis Simulation using Stand-Alone Cadence Verilog.”
  \item Section 5 “Verilog RTL Synthesis using Synopsys.”
  \item Section 6 “Post-Synthesis Simulation and Timing Analysis of the Gate-Level Netlist.”
  \item Section 7 “Cadence Timing Analysis Tool: Pearl.”
  \item Section 8 “Running the tools in Scripts.”
  \item Section 9 “Remote Use of Tools.”
  \item Section 10 “PC Tools.”
  \item Section 11 “References.”
\end{itemize}

The tools used for design capture may depend upon the complexity of the design being implemented. Where simple designs may require only the use of the stand-alone Cadence Verilog tool and Signalscan, more complex design will probably require the use of the Cadence Composer tools.

4 Pre-Synthesis Simulation using Stand-Alone Cadence Verilog.

4.1 Initial Setup.

This section describes the steps necessary to configure your environment and obtain the files needed to complete this tutorial. This section will only need to be accomplished once.

1. You are encouraged to create a directory for your ECE-520 work in your home directory. You should then create directories for your homework, Cadence, and miscellaneous work under it. The figure below illustrates this suggested hierarchy, and the sequence that follows will create these initial directories for you.
Figure 2: File Folders

```
 eos> mkdir ~/ece520
 eos> mkdir ~/ece520/cadence
 eos> mkdir ~/ece520/hw
 eos> mkdir ~/ece520/misc
```

Note: The tools that we use in this course generate a large number of files during each lab. These files are far easier to use and maintain when they are well organized from the start. You are therefore encouraged to follow this or some other logical plan for arranging your work.

2. The following steps will create a working directory for the down-counter design in your Cadence locker, change your current working directory to the down-counter directory, and copy the files required for pre-synthesis simulation to there.

```
 eos> mkdir ~/ece520/cadence/counter
 eos> cd ~/ece520/cadence/counter
 eos> attach ece520_info
 eos> cp /ncsu/ece520_info/tutorials/tutor1/bin/* .
```

Ensure that your counter directory now has the files named all.cmd, count.dc, count.v, count_final.cmd, runmeall*, simmax*, simmin*, simpost*, std-cell.tech, testcount.v, test-max.v, testmin.v, testpost.v and testpre.v.

4.2 Simulation using only Stand-Alone Cadence Verilog.

This section will describe the steps used to simulate and verify a design using the stand-alone Cadence Verilog tool in a single textual interface, such as that found in a dial-up session (Section 9 on page 26.)

1. With a text editor, open and inspect the files named count.v and testpre.v. The counter module in count.v file is a Verilog RTL “definition” of the counter, and counter ul contained within the test_fixture module of the testpre.v file is an “instance” of this counter. The first line on the testpre.v file tells the Cadence Verilog tool to include the counter definition during compilation. Within the test_fixture module, you should also note the following “system tasks” and their purpose:
- `$display("text with format specifiers", signal, signal, ...);` prints the formatted message once when the statement is executed during the simulation.
- `$dumpfile("file name");` opens/creates the named “value change dump” file for writing the simulation results in a format that can be used later with an external viewer. See Chapter 20 in the Verilog-XL Reference for more information.
- `$dumpvars;` “probes” and saves signal waveforms on all nets of the design in the opened results file.
- `$finish;` finishes the simulation and exits the simulation process.

2. Enter the following at your EOS prompt:

```plaintext
eos> add cadence
eos> verilog testpre.v
```

You should see results similar to the following:

![Figure 3: Verilog-XL -- First Run Pre-syntheses Results](image)

Notice the output created by the `$display("Welcome to the World of Verilog \n");` system task.

**Note:** The telephone number displayed for technical assistance from Cadence is **not** for use by university students. If you need assistance, you should consult the references listed at the end of this document.
3. Using a text editor of your choice, open the `testpre.v` file and un-comment the line:

```verbatim
$monitor("Time =%d;   Clock =%b;   In =%h;   Zero =%b", $stime, clock, in, zero);
```

The `$monitor("text with format specifiers", signal, signal, ...);` system task monitors the signals listed and prints the formatted message whenever one of the signals changes.

4. Ensure you save the modified `testpre.v` file, then re-run the simulation by entering the following at your EOS prompt:

```
eos> verilog testpre.v
```

You should see results similar to the following:

![Figure 4: Verilog-XL -- Second Run Pre-syntheses Results](image)

Now note the more useful output created by the `$monitor("Time %t, ..."> system task. Take a moment to verify that the down counter behaves as expected.

### 4.3 Verification using Stand-Alone Cadence with Signalscan.

This section will describe the steps used to verify a design using the stand-alone Cadence Verilog tool output in conjunction with the Signalscan graphical waveform viewer when in an X-
Window environment.

1. Ensure that `counterpre.vcd` file was created during the simulation above.

2. To invoke the Signalscan waveform display tool, enter the following at your EOS prompt:
   
   ```
eos> signalscan &
   ```

   After a moment, the following Signalscan waveform display window should appear:

   ![Figure 5: Waveform opening window](image)

   *Note*: If you have not added the Cadence tools to your path during this session, you will need to enter “add cadence” at your EOS prompt before you can use the Signalscan tool.

3. From the Signalscan window menu bar, select:
   
   **File -> Open Simulation File**...

   The following window should appear:
4. Set the filter in the top-line to look for *.vcd files. In the Load Database window, left-click with the mouse to highlight counterpre.vcd in the Files box. Then left-click on the button labeled OK. If a file translation window appears, choose OK.

5. From the Signalscan window menu bar, select:

Windows -> Design Browser

The following Signalscan Browser should appear:

6. In the box labeled Instances, select test_fixture to move down through the simulation hierarchy.
7. To select all of the signals, simply click and hold the left mouse button while you drag the pointer over the desired names in the nodes/variables in current context box. This should highlight all of the appropriate signals present at the test_fixture level of the simulation. The Signalscan Browser window should now appear as shown:

![Figure 8: Signalscan -- Browser](image)

8. After you have highlighted the desired signals, left-click on the Add, close button

9. A graphical representation of the simulated signals should now be seen in the Signalscan waveform display window. Left-click on the ZmOutXFull button to expand the signals to fill the waveform display window. When you are finished, the Signalscan window should appear similar to the one below:

![Figure 9: Signalscan -- Final Waveform Display](image)

*Note:* The box on the left-hand side of the waveform display window shows the corresponding signal names. You can change the width of this box if necessary by dragging the divider between the left-hand and right-hand sections of the window.
You are encouraged to explore the features of this tool and in particular, note that you can save
the current setup parameters, close the waveform file, re-run the simulation, and then restore
the previous setup parameters with the new simulation results. These features are available
from the File -> pull-down menu.

10. When you are finished with the waveform display, select:
    File -> Exit
from the Signalscan menu bar.

5 Verilog RTL Synthesis using Synopsys.

5.1 Initial Setup.
This section describes the steps necessary to configure your environment for using Synopsys.
This section will only need to be accomplished once.

1. Enter the following at your EOS prompt to copy the file required for configuring your sys-
tem environment to use Synopsys:

   eos> cp /ncsu/ece520_info/tools/.synopsys_dc.setup ~

2. Enter the following to ensure that your root or home directory now has the file named
   .synopsys_dc.setup:

   eos> ls ~/.synopsys_dc.setup

5.2 Synthesis using Synopsys Design Analyzer.
This section will describe the steps used to synthesize an RTL design using the GUI Synopsys
Design Analyzer and Command Window interfaces when in an X-Window environment.

1. With a text editor, open and inspect the file named count.dc. This file contains a list of Syn-
opsys commands that will be executed sequentially by the Design Analyzer. Note that each
command has been fully commented for you so that you can recognize and understand the
steps taken during synthesis to produce an optimal design that will function properly within a
set of given constraints. Please take a moment to read carefully over the contents of this file
and note the following commands and their purpose:

   • target_library = {"ms080cmosxCells_XXW.db"} specifies the library whose cells
     will be used to create the netlist for the design. In this case a CMOSX worst case
     library which will be used to check for setup timing violations.
   • link_library = {“ms080cmosxCells_XXW.db”} specifies the library whose cells are
     used in the current design netlist.
   • translate replaces each cell in the current design with the closest matching functional
     cell from the target library. Since no optimization takes place, a design that met timing
     constraints previously may fail to once the cells are translated to the new technology
     library.
   • write_timing -output count_*.sdf -format sdf-v2.1 creates a separate “Standard
     Delay Format” file containing timing constraint information for cells used in the
     design. This is allows for “forward annotation” of the delay values to the Cadence tools
2. To invoke the Design Analyzer tool, enter the following at your EOS prompt:

```
eos> add synopsys
eos> design_analyzer &
```

After a moment, the following Synopsys Design Analyzer window should appear:

![Design Analyzer Opening Window](image)

**Figure 10: Design Analyzer Opening Window**

This window provides a graphical user interface to the Synopsys synthesis tool and is used to display and interact with symbol and schematic representations of the gate level circuits that result from synthesis. An additional window, referred to as the Command Window, is provided as a textual interface to the synthesis tool through the use of Synopsys commands.

3. To access the Command Window, select:

```
Setup -> Command Window...
```

from the Design Analyzer menu bar. After a moment, the following Command Window should
Figure 11: Design Analyzer -- Command Window

Notice that at the bottom of the Command Window there is a box with a design_analyzer prompt. This prompt acts as the command line for entering Synopsys commands manually.

4. Since you already have the count.dc script file containing the necessary commands for synthesis, all you have to do is enter the command to tell Synopsys to include the contents of the file. There are two ways to enter the command from within design_analyzer.

4a. The first method is to use the Design Analyzer menu bar; Select: Setup -> Execute Script...
After a moment, the following Execute File Window should appear:

Figure 12: Design Analyzer -- Execute File Window
Left click on count.dc and choose OK.

4b. The second method is to use the Command Window. At the design_analyzer prompt, enter:

```
  design_analyzer> include count.dc
```
Either one of these commands will cause Synopsys to read and execute the commands from the script file. You should see the contents of the file echoed to the Command Window along with responses from the synthesis tool. Even though these will scroll through rapidly at times, you will still have access to the results later on since they are simultaneously echoed to a view_command.log file in the working directory.

Note: Without exception, you must determine and correct all conditions that lead to “error” statements. You can choose to accept conditions that lead to “warning” statements, but only when you determine that the ramifications are acceptable within your design.

5. The script will take a few moments to run. You can determine when synthesis is complete by observing the design_analyzer prompt in the Command Window. When a blinking cursor re-appears, the script should have been executed completely. Your Synopsys Design Analyzer window should now appear similar to the one pictured below:

![Design Analyzer Results Window](image)

Figure 13: Design Analyzer -- Results Window

6. In the Synopsys Design Analyzer, left click on the counter symbol in order to select it. You should notice that it’s border becomes a dashed line and that the down arrow button in the lower left-hand side of the window becomes active. Double left-click on the button to see a “symbol view” of the synthesized down counter. The symbol should appear similar to the one pictured below:
7. You should now see that the *Symbol View* button, pictured as a black box with inputs and outputs on the left-hand side of the window, is active and highlighted, and that the *Schematic View* button, pictured as an AND gate, is also active:

![Figure 15: Design Analyzer -- Symbol View button](image)

You can use these to select the desired view to display in the *Synopsys Design Analyzer* window. Left-click on the schematic view button to see the synthesized down counter schematic. Your *Synopsys Design Analyzer* window should now appear similar to the one below:
8. To plot the current view select:

   File -> Plot...

from the menu bar.

You are encouraged to explore the features of this tool and in particular, note that you can
highlight specific circuit path sections of the schematic based upon their parameters such as
the critical path, the “max” path and the “min” path by selecting:
   Analysis -> Highlight -> <Desired Path Parameter>

from the menu bar.

9. When you are finished, select:

   File -> Quit

from the Synopsys Design Analyzer menu bar.

5.3 Synthesis using Synopsys DC Shell -- Interactive.

In Section 5.2, you used the Design Analyzer window as a graphical interface to the Synopsys
synthesis tool -- Design Compiler. Design Compiler has a command line interface called DC
Shell. This section will describe the steps used to synthesize a design using DC Shell.

1. Using a text editor of your choice, open the count.dc file and un-comment the following
lines at the end of the file:

   create_schematic -size infinite -gen_database
   create_schematic -size infinite -symbol_view
   create_schematic -size infinite -hier_view
   create_schematic -size infinite -schematic_view
   plot_command = “cat>plot.ps”
   plot -hierarchy

These additional commands are needed to generate a postscript output of the schematic view.
2. Enter the following at your EOS prompt:
   ```
   eos> dc_shell
   ```
   *Note:* If you have not added the Synopsys tools to your path during this session, you will need to enter “add synopsys” at your EOS prompt before you can use the DC Shell tool.

3. In a moment, your EOS prompt will be replaced by a dc_shell prompt. Enter the following at the dc_shell prompt:
   ```
   dc_shell> include count.dc
   ```
   The textual interface will echo the synthesis results much like the Command Window did previously, except that when executing a “report” command, the scrolling of the display will pause until you press the space bar once and then press the enter key.

4. When the script file has been executed, the dc_shell prompt will return. To exit DC Shell, enter the following at the prompt:
   ```
   dc_shell> quit
   ```
   *Note:* To use the count.dc script again with the Design Analyzer tools, you should comment out the additional commands you entered above.

5.4   Synthesis using Synopsys DC Shell -- Non-interactive.
In Section 5.3, you used the DC Shell as an interactive tool. DC Shell can also be used non-interactively such as being called from another script or Makefile. This section will describe the steps used to synthesize a design using DC Shell in a single command.

1. Using a text editor of your choice, open the count.dc file and un-comment the following lines at the end of the file:
   ```
   exit
   ```
   This additional command is needed to terminate DC Shell at the end of the script.

2. Enter the following at your EOS prompt:
   ```
   eos> dc_shell -f count.dc
   ```
   *Note:* If you have not added the Synopsys tools to your path during this session, you will need to enter “add synopsys” at your EOS prompt before you can use the DC Shell tool.

   The textual interface will echo the synthesis results exactly the same as in Section 5.3.

4. When the script file has been executed, the eos prompt will return.

   *Note:* To use the count.dc script again interactively, you should comment out the additional command you entered above.

5.5   Comments on Using DC-shell
After using DC shell, you should review over the view_command.log file and satisfy yourself that there are not ERRORs and that none of the WARNINGs will result any design implementation problems. You might also want to look at the postscript file that contains the schematic
of your final design to check that it ‘looks OK’.

6 Post-Synthesis Simulation and Timing Analysis of the Gate-Level Netlist.

This section will describe the steps used to simulate the gate level design created by Synopsys using Standard Delay Format (SDF) files to “forward annotate” best and worst-case timing information to the Cadence Verilog tool.

1. The simpost* file is a script file containing a rather lengthy command to invoke the stand-alone Cadence Verilog tool with the gate level netlist created by Synopsys. At your EOS prompt, enter the following:

   eos> simpost

   This will simulate the netlist created by Synopsys without any of the timing information created by Synopsys.

2. The simmax* file is a script file containing a rather lengthy command to invoke the stand-alone Cadence Verilog tool with the gate level netlist created by Synopsys. This command also causes Cadence to incorporate the maximum timing delay information created by Synopsys into the simulation. At your EOS prompt, enter the following:

   eos> simmax

   This will cause Cadence to simulate much as before, except that the waveform database is now called wavesmax.shm. You should also note that the Cadence response includes a statement that the SDF “back annotation” completed successfully.

   Note: If you have not added the Cadence tools to your path during this session, you will need to enter “add cadence” at your EOS prompt before you can proceed with this section.

3. This step will mimic the one above except that it will do so for the minimum timing delays. At your EOS prompt, enter the following;

   eos> simmin

   Now the Cadence simulation will save the results to a wavesmin.shm database.

4. As before, enter the following at your EOS prompt to invoke the Signalscan tool;

   eos> signalscan &

   In a moment, a Signalscan waveform display window should appear.

5. Using the Signalscan window menu bar, select;

   File -> Open Simulation File...

   to open the countermax.vcd file.

6. Again using the Signalscan waveform display window menu bar, select;

   File -> Open Simulation File

   to open the countermin.vcd file.
7. As before, use the *Signalscan* menu bar to select;  
**Windows->Design Browser...**
8. From the *Signalscan Browser* that appears, choose the file countermax.dsn from the *Instances in current context* box to access the maximum timing delay data.

9. Traverse the hierarchy and as before, add all of the signals to the waveform display that are contained in the *test_fixture* instance.

10. Again from the *Signalscan Browser*, choose the countermin.dsn file from the *Current File* pull-down box to access the minimum timing delay data.

11. Traverse the hierarchy and add the signals to the waveform display as above.

12. Click the Add,Close button in the *Signalscan Browser* and carefully examine the waveforms in the waveform window. In particular, you should note a significant difference between the timing of the *zero* output from the counter.

13. When you are finished with the waveform display, select;  
**File -> Exit**  
from the *Signalscan* menu bar.

7 Cadence Timing Analysis Tool: *Pearl.*

*NOTE:* We do not have a full set of timing models for *Pearl.* Though this part of the tutorial will work correctly, *Pearl* will most likely not work on your own design.

7.1 Introduction to *Pearl*

*Pearl* is a static timing analysis tool. It specifically designed for timing analysis. It has two versions, *Pearl Cell* and *Pearl Full Custom.* *Pearl Cell* is able to analyze gate-arrays and standard cell designs. *Pearl Full Custom* has a capability to analyze full custom and structured custom designs. It also gives access to *Pearl’s* transistor level capabilities.

*Pearl* has several features. The following is the list of its features.

- **Full Design Coverage:** *Pearl* is able to trace and analyze all the paths in the circuit where as a dynamic timing analyzer can only checks paths exercised by the simulation vectors.
- **Accurate Delay Calculation:** To ensure accuracy, it takes the gate slew rate and inter-connection resistance and capacitance into account during delay calculations.
- **Fast Analysis Time:** *Pearl* uses smart search algorithms to reduce the time spent during path searching.
- **Two types of Modeling:** *Pearl* supports both gate transistor level modeling.
- **Mixed Level Modeling:** *Pearl* can analyze mixed module levels of design.
- **Different Design Formats:** It supports different design styles and netlist formats.
- **Number of Analysis types:** *Pearl* provides a number of analysis types. These analysis types are long path identification, timing verification, minimum clock cycle identifica-
tion, suppressing false paths and simulation of selected delay paths with Spice. It has a variety of reports to help the designer examine the circuit network and delay calculations.

During the timing analysis *Pearl* uses several files shown in the Figure 17.

![Figure 17: Pearl data file](image)

- **Command File** specifies the types of analysis to run, the input files to read, the types of reports to generate.
- **Technology File** contains the technology information about the design.
- **GCF File** contains the timing library and operating conditions of the design.
- **TLF Timing Library Files** contains pin-to-pin delay information and timing checks for gate level primitives.
- **Netlist Files** describe the design.
- **Cell Declaration File** defines transistor level latch and register circuit topologies.
- **Parasitic Files** contain parasitic data for cell level and transistor level designs.
- **SDF Delay File** represents interconnection and gate delays and timing checks.
- **Spice Input Deck** contains a complete input deck for the transistors on the selected critical delay path for Spice simulation.
- **Reports**: Analysis results are written to Report files.

In this tutorial, gate level analysis with *Pearl* is introduced. Analysis is done using your counter design. The files that you need to run this tutorial are `counter_final.v`, `count_final.tlf`, `std_cell.tech`, and `count_final.cmd`.

`Counter_final.v` is the synthesized verilog netlist of the `counter.v` that you produced with Synopsys. `Std_cell.tech` is the technology file seen in Figure 17.

### 7.2 General information about running *Pearl*

You can run *Pearl* in batch and in interactive mode. In this tutorials we will show you how to run *Pearl* in interactive mode. Following is some general information about running *Pearl*.

- *Pearl* commands are **not** case-sensitive.
- You can continue long commands by ending the line with a back-slash \\ preceded by a space.
• Use **help** or ? to list all *Pearl* commands with their arguments.
• Use **Quit** to exit *Pearl*.
• Use **Ctr-C** to interrupt a command while it is executing.
• Use **Undo cmd** to reverse the effects of a command.
• A Command file contains any *Pearl* commands. Comment lines begin with the pound character (#). You can use **alias** in command file to define a shorthand for commands. See command file *count_final.cmd*.

7.3 **Running Pearl**

Change into your working directory.

```plaintext
eos> cd ~/ece520/cadence/counter
eos> pearl
```

You should get a pearl prompt that looks like this:

```plaintext
cmd>
```

**Note:** If you have not added the *Cadence* tools to your path during this session, you will need to enter “add cadence” at your EOS prompt before you can use the *Pearl* tool.

Next *Pearl* will read in a command file and executes the commands one by one (Figure 18). Before you do it, we suggest to look at the command file to understand these commands.

```plaintext
cmd> include count_final.cmd
```

**Note:**

- The first line is a comment.
- The next two lines define two short names **dn** and **sp** using the **Alias** command.
- Line five is a comment. Note that the rest of the comments (#number) show the order in which files must be read into Pearl.
- **ReadTechnology** command reads the standard cell technology. This file specifies the power and ground node name, the logic threshold, the default rise time on input nodes, and data to estimate stray capacitance.
- **ReadTLF** command reads the TLF timing models used by the counter circuits. These models specify pin-to-pin delays, output slew, and timing checks for each of the gate types used in the design.
- **ReadVerilog** command reads the Verilog gate-level netlist.
- **TopLevelCell** command declares the top-level cell in the design.
7.3.1 Finding the Longest Paths

Next you will identify the longest paths triggered by the rising edge of the clock.

```
cmd> SetPathFilter -same_node

cmd$> FindPathsFrom clock ^
```

*Pearl* prints out the summary of the 10 longest paths (Figure 19). Path delay and the end node of the path are also reported.

```
cmd> ShowPossibility

or

cmd> sp
```

Note:
- ^ and v indicate the rising and falling edges.
- Path end is at the output ports or register and latch inputs.

You also can look at the detail description of the path.
The detail worst delay path report is shown in Figure 19. The delay path is a list of alternating devices (gates) and nodes.
	node1 -> device1 -> node1 -> device2 -> node3 ...

![Figure 20: Detailed report of possibility 1.](image)

Note:
- In the report, an asterisk (*) at the beginning of the line shows the top 20 percent of the total delays.
- Delay is the cumulative delay to node and Delta is the delay from node to the next node.
- Cell is the type of the Device.

### 7.3.2 Examining Rise and Fall Times for Nodes

Next you will examine the minimum and maximum rise and fall times for any node in the circuit.

```
cmd> ShowDelays zero
```

*Pearl* report the rising edge of the CLK input causes the node to rise after 6.21ns to 7.44ns range and fall after 6.21ns to 7.44ns range (Figure 21).

You also can show the delay path for that report (Figure 21).

```
cmd$> ShowDelayPath zero ^
```

```
cmd$> ShowDelayPath zero v
```
Figure 21: Rise and fall time report for node zero.

Note: If the minimum and maximum rise and fall time are different, *Pearl* prints a range. You can use the `ShowDelayPath -min node_name` to check the shortest path.

### 7.3.3 Verifying the Timing of the Design

Next you will check of the counter design works for the specified clock timing.

1. Define the clock and the cycle time.
   ```
cmd$> Clock clock 0 25
   cmd$> CycleTime 50
   ```

2. Verify the timing of the design.
   ```
cmd$> TimingVerify
   ```

*Pearl* compares the difference of the data and clock arrival times to the minimum setup and hold timing checks (Figure 22).

Note:

- See ECE520 notes for the detail about the setup and hold time violations and calculations.
- Constraint violation means the slack is negative.
3. Detail report.

```cmd
sp
```

The detailed report of a timing check has the following parts (Figure 23).

- The first line shows the type of timing check.
- The second line shows the slack time and the name of the register or latch that has the timing constraint.
- The third line shows the clock edge that causes the local clock edge at the register and the time it occurs. It also reports that Pearl adds a clock cycle to the local clock arrival time.
- The fourth line shows the required setup time.
- The fifth line shows the clock edge that causes the data to change and the arrival time at the input to the register.
- The sixth line is required cycle time.
- The rest of the display is the delay path to the data input. The format is as the same as we have seen in Figure 20.
Note: all.cmd has all of the pearl commands given in this tutorial. To run in batch mode, at the EOS prompt, type:

```
eos> pearl all.cmd
```

### 8 Running the tools in Scripts.

To ensure process repeatability, it is a good idea to use scripts. Examine the file runmeall. This script will run through all the steps of the tutorial except the waveform viewer. At the EOS prompt, type:

```
eos> runmeall
```

*Note:* If you have not added the *Cadence* and *Synopsys* tools to your path during this session, you will need to enter “add cadence” and “add synopsys” at your EOS prompt before you can use the *Pearl* tool.

### 9 Remote Use of Tools.

Once you have established a telnet session you may run a great many of the commands in this tutorial.

- All the commands in Section 4.2 can be run remotely. The `$display` and `$monitor` statements are the most helpful commands for remote debugging. You will want to use them heavily in your test fixtures. You can also place them inside your RTL verilog modules for testing but *you will have to comment them out before attempting syntheses.*

```
eos> verilog testpre.v
```

- The waveform viewer tools in Section 4.3 can not easily be viewed remotely, although the waveform files will still be saved to your account. You must either view them on campus or establish an PPP connection for remote viewing. (Establishing a PPP connection will NOT be worth your while. It is too slow).

- **None** of the commands in Section 5.2 using the design_analyzer tool can be run remotely.

- Section 5.3 can be run remotely.

```
eos> dc_shell
dc_shell> include count.dc
dc_shell> quit
```

- Section 5.4 can be run remotely.

```
eos> dc_shell -f count.dc
```

- Make sure you check the view_command.log file for all ERROR and WARNING messages. All errors must be fixed and you need to understand why each warning message will not result in a design problem. You should also download and view the postscript plot generated by dc_shell.

- All commands in Section 6 except the waveform viewer can be run remotely.

```
eos> verilog testpost.v
eos> simmax
eos> simmin
```
• All of the commands in section Section 7.3 can be run remotely.
  
  `eos> pearl all.cmd`

In Section 11, Iview and Openbook can not be run remotely, although you can access help through dc_shell through the use of:

  `dc_shell> help <command name>`

An example of what can be run remotely is in “runmeall”.

  `eos> runmeall`

*Note:* If you have not added the Cadence and Synopsys tools to your path during this session, you will need to enter “add cadence” and “add synopsys” at your EOS prompt before you can run the tools.

10  PC Tools.

10.1  DOS Veriwell

VeriWell is an interpreted simulator. This means that when VeriWell starts, it reads in the source models, compiles them into internal data structures, and then executes them from these structures. The structures contain enough information that the source can be reproduced from the structures (minus formatting and comments).

Once the model is running, the simulation can be interrupted at any time by pressing control-C (or the "stop" button if using a graphical user interface). This puts the simulator in an interactive command mode. From here, VeriWell commands and Verilog statements can be entered to debug, modify, or control the course of the simulation.

10.1.1  Installation

10.1.1.1  At school:
  • Copy files from /afs/eos.ncsu.edu/info/ece/ece520_info/pc-tools to a floppy disk, using the same directory structure as in pc-tools
  • Copy count.v and testpre.v to a floppy disk.

10.1.1.2  On your home PC:

At the “C” prompt, type:

  `C:\> mkdir c:\veriwell`
  `C:\> mkdir c:\veriwell\examples`
  `C:\> cd c:\verilwell`

Place the floppy disk created in Section 10.1.1.1 into drive A.

  `C:\> copy a:\verilog\* .`
  `C:\> copy a:\verilog\veriwell\* .`

The following files should have been copied over:

  • `README.1ST`  IMPORTANT INFORMATION ABOUT VERIWELL.
  • `INSTALL.TXT`  Installation instructions.
  • `VERIWELL.EXE` VeriWell for DOS; requires DOS4GW.
  • `VERIWELL.DOC` Documentation for VeriWell.
To get example files, type:

C:\> copy a:\verilog\examples\* examples

Editing system files:

C:\> cd c:\
C:\> edit autoexec.bat

• Append "C:\veriwell" to the pre-existing SET PATH command.
• Make sure a semicolon exists between the old path and your addition.
• Save and exit autoexec.bat.

C:\> edit CONFIG.SYS, type

• If FILES command does not exist -- type “FILES=20”.
• If FILES command does exist.
  • If less than 20 -- up number of files to 20.
  • If greater than 20 -- leave file alone.

Save and exit file.
Restart your computer

10.1.2 Initial Setup for Tutorial

At the “C” prompt, type:

C:\> cd C:\veriwell
C:\> mkdir c:\veriwell\ece520
C:\> mkdir c:\veriwell\ece520\cadence
C:\> mkdir c:\veriwell\ece520\cadence\counter
C:\> cd c:\veriwell\ece520\cadence\counter

Place the floppy disk containing count.v and testpre.v into drive “A”

C:\> copy a:\count.v .
C:\> copy a:estpre.v .

10.1.3 Running DOS Veriwell

At the “C” prompt, type:

C:\> veriwell testpre.v

Note the errors involving all the $shm commands. The $shm are Verilog-XL specific commands.

At the “C” prompt, type:

C:\> edit testpre.v

• Comment out three $shm commands.
• Save and exit the file.
To rerun the file:

C:\> edit testpre.v
All screen output is captured in the file VERIWELL.LOG.

Note: C:\veriwell\veriwell.doc is an excellent reference source for this program. It covers the differences between Verilog-XL and Veriwell. The document covers verilog syntax allowed and understood by the Veriwell simulator as well as a list of command for interactively using the simulator.

10.1.4 Basic Information about Veriwell

10.1.4.1 Command line:
- If there is more than one file, then each needs to be specified on the command line.
- The order that the files appear in the command line is the order that the files will be compiled.
- VeriWell will enter interactive mode before execution with the "-s" (stop) command line option.
- VeriWell will enable trace mode at the beginning of the simulation with the "-t" (trace) command line option.
- Command files are read by VeriWell using the "-f" option.

10.1.4.2 Command Interaction:
- VeriWell allows commands and statements to be entered interactively. This can be used to control, observe, and debug the simulation.
- When interactive mode is entered, the prompt will look like this:
  C1>
  Where "C" refers to the fact that VeriWell is in command mode, and "1" refers to a sequential number of the completed command.

There are a number of interactive commands that can be entered at the command prompt.
- One is "." (period). This resumes execution of the simulation.
- Another is "," (comma). This executes one Verilog statement and displays the next statement to be executed.

Also, many Verilog commands can be typed in at the command line.
- $display; can be typed to view the current value of any variable.
- $scope; can be typed to traverse the hierarchy.
- $finish; can be typed to exit the simulator.
- $settrace; enables Trace mode.
- $cleartrace; disables Trace mode.

10.2 Windows Veriwell -- Windows98
VeriWell for Windows is a graphical front-end to easily control the simulation and debugging of VeriWell models. This allows for integrated editing and modification of Verilog models and the support of "projects" which are collections of files comprising
a particular model.

10.2.1 Installation

- **Window 1:**
  - Left mouse click on "My Computer" Icon.
  - Left mouse click on drive "C" icon.
  - Left mouse click on "veriwell" icon.
  - Choose file->new folder.
  - Name the folder “Veriwin”.
  - Descend into “Veriwin” folder.

- **Window 2:**
  - Left mouse click on "My Computer" icon.
  - Left mouse click on floppy drive "A" icon.
  - Left mouse click on "veriwell_windows" icon.
  - Select both files and drag over to "Window 1" -- the Veriwin folder.

- **Window 1:**
  - Make sure both files appear.

- **Window 2:**
  - Click up one directory.
  - Select pkunzip and drag to "Window 1".

- **Window 1:**
  - Make sure file appears.

- **Window 2:**
  - Close this window.

- **Window 3:**
  - Choose Start->Programs->DOS Prompt.
  - Cd into c:\veriwell\windows
  - pkunzip vwin205.
  - Choose append to readme when asked.
  - Exit.
  - This will close window 3.

- **Window 1:**
  - The Veriwin folder should be the only window open.

10.2.2 Running Window Veriwell

- Double Left mouse click on green Veriwell icon.
- In window that appears, choose file->open.
- Change to c:\veriwell\ece520\cadence\counter
- Choose testpre.v
- Choose Window->Tile
- Chose Project->New ======> Type Counter
- Chose Project->Add file ======> Select testpre.v
- Chose Project ->Run
- Chose Project->Continue
10.2.3 Viewing Waveforms

- Edit testpre.v and add “$vw_dumpvars” just before $shm_open.
- Save testpre.v
- Choose Project->Run
- Choose Project->Continue
- File->Open Wavefile
- Choose wavefile.vwf
- Left mouse click on right most window button.
- In the window that pops up, left click new group and name it “test”.
- Left mouse click on test_fixture until signal names appear.
- Left mouse click on “add all”.
- Now close this window.
- In the waveform window, waveforms should have appeared.
  - The "+" symbol is the zoom in.
  - The "-" is the zoom out.
  - The button two buttons to the right of zoom out is zoom full.
  - The green buttons are the run, step, continue, stop etc.
- Chose Project ->CloseProject
- File->exit

10.2.4 VeriWell Basics

VeriWell is a full featured, OVI compliant Verilog Simulator. VeriWell includes integrated project management, an integrated editor, an integrated waveform viewer, and a VERILOG Simulator.

- $vw_groupfile("filename"); Use to restore a previously save set of signal groups from "filename".
- $vw_group("groupname", <signal> <, signal>*); Use to create a new signal group named "groupname". The list of signals will be added to the group. Only signals that have been probed via the $vw_dumpvars() task may be viewed.
- $vw_dumpvars; Use to specify the set of signals to probe for later viewing.

10.2.4.1 VeriWell Console Window

- When you start VeriWell, the console window is opened immediately and available for use.
- Menu or Button Commands:
  - Run: Start a compilation or simulation.
  - Restart: Restart a compilation or simulation.
  - Continue: Continue simulation.
  - Stop: Stop simulation.
  - Exit: Exit simulator.
  - Step: Advances simulator one time step.
  - Trace: Advances simulator one time step and traces line executed.
10.3 Comments on Using Veriwell
We have not spent a lot of effort using Veriwell here at NC State, so you are pretty much on your own for tool-specific problems. Please do not ask us for support. However, you should find it useful for pre-synthesis simulation. You will NOT be able to use if for post-synthesis simulation, however.

11 References.

11.1 On-Line Documentation.
The available on-line documentation for the Cadence tool suite is called OpenBook. It is accessed by entering the following at your EOS prompt:

```
eos> add cadence
eos> openbook &
```

The available on-line documentation for the Synopsys tool suite is called IView. It is accessed by entering the following at your EOS prompt:

```
eos> add synopsys
eos> iview &
```

There is additional, “man page” style help available for Synopsys commands when using DC Shell. It is accessed by entering the following at the dc_shell prompt:

```
dc_shell> help <command name>
```

The available on-line documentation for the Pearl tool suite is called OpenBook. It is accessed by entering the following at your EOS prompt:

```
eos> add cadence
eos> openbook &
Openbook -> Timing -> Pearl User Guide
```

Chapter 4 explains all commands for Pearl.

11.2 Texts.
• VeriWelltm User’s Guide 2.0, Wellspring Solutions, Inc.;P.O. Box 150;Sutton, MA 01590;